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MULTIPURPOSE FARMING ROBOT

Prof. P. J. Waditke*[1], Miss. Tamboli Namara Ejaj[2], Mr. Chikhale Chaitanya Machhindra[3], Miss. Shinde Sakshi Santosh[4]

[1]Lecturer, Department of Mechatronics, P. Dr. V. V. P. INST. OF TECH.&ENGG(POLYTECHNIC).Loni 413736.

[2,3,4]Student, Department of Mechatronics, P. Dr. V. V. P. INST. OF TECH.&ENGG(POLYTECHNIC).Loni 413736.

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***Corresponding Author: Prof. P. J. Waditke**

Lecturer, Department of Mechatronics, P. Dr. V. V. P. INST. OF TECH.&ENGG(POLYTECHNIC).Loni 413736.

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ABSTRACT

Agriculture plays a significant role in the economy, but traditional farming methods need significant manual labor & time. With the development of automation & robotics, agricultural processes can be enhanced through smart machines. A Multipurpose Farming Robot is an automated agricultural system developed to perform multiple tasks like seed sowing & water spraying in farmland. The robot requires a microcontroller, motor drivers, & DC motors to move through the field, while a seed hopper & spraying mechanism help operate farming operations effectively. The system decreases human effort & improve accuracy in farming activities. The usage of sensors & programmed control enables the robot to control automatically, ensuring proper seed placement & efficient irrigation. This technology supports modern smart farming by saving time, decreasing water consumption, & enhancing crop productivity.

INTRODUCTION

Agriculture is one of the main crucial sectors for food production & economic growth. However, traditional farming practices often need a large amount of manual labor, which can be takes a lot of time & physically demanding. Farmers also face challenges like labor shortages, inefficient water usage, & inappropriate seed distribution. The robot is controlled using a microcontroller like Arduino, which processes programmed instructions/commands to control motors & pumps. By integrating mechanical systems & automation, the robot helps

increase efficiency, precision, & productivity in agricultural operations. Such systems represent an significant step toward the advancement of smart farming technologies.

To conquer these challenges, automation technologies are being proposed into agriculture. A multipurpose farming robot is an automated machine developed to guide farmers by performing various farming operations with minimum human connection. The robot can move across farmland using wheels powered by DC motors & perform tasks like seed sowing & water spraying.

LITERATURE SURVEY

Researchers have been discovering robotic solutions to enhance agricultural productivity & decrease manual labor. Early farming automation systems mainly focused on single operations like irrigation or soil monitoring. However, modern agricultural robots are developed to perform multiple operations simultaneously.

The literature recommends that multipurpose farming robots are an effective solution for modern agriculture, especially in countries where labor shortages & enhancing demand for food production require more efficient farming practices.

Studies published by IEEE highlight the advancement of autonomous agricultural robots capable of performing tasks like planting, fertilizing, & crop monitoring. These robots help increase efficiency & decrease the dependency on manual labor.

Research from Elsevier illustrates that robotic farming systems can enhance crop productivity while reducing water & fertilizer consumption. The integration of microcontrollers, sensors, & automated control systems allows robots to perform agricultural operations with high accuracy.

PROPOSED SYSTEM

The proposed system is an automated farming robot developed to perform seed sowing & water spraying tasks in agricultural fields.

A. System Overview

The system contains robotic vehicle powered by DC motors & controlled by an Arduino microcontroller. The robot moves across the farmland using wheels connected to the chassis. A seed hopper stores seeds, which are released into the soil at regular intervals during movement.

A water tank & pump system are integrated into the robot to spray water through a nozzle. The motor driver controls the movement of the robot, while the microcontroller controls the seed sowing & water spraying processes based on programmed instructions/commands.

B. Key Components

Hardware Components

- Microcontroller (Arduino)
- Motor Driver (L298N)
- DC Motors
- Wheels
- Battery (Power Supply)
- Water Pump
- Water Tank
- Spray Nozzle & Pipe
- Seed Hopper (Container)
- Connecting Wires & Chassis

Software Components

- Arduino IDE
- Embedded C / Arduino Programming
- Motor Control Program
- Pump Control Program
- Seed Sowing Control Program

C. Working Principle

1. The robot is powered by a renewable battery attached to the microcontroller & motor driver.

2. The Arduino microcontroller obtains programmed instructions to control the movement & farming operations.

3. The motor driver controls the DC motors that rotate the wheels, enabling the robot to move across the farmland.

4. As the robot moves forward, the seed hopper releases seeds into the soil at predetermined intervals.

5. Simultaneously, the water pump draws water from the tank & transfers it to the spray nozzle.

6. The spray nozzle divides water evenly over the planted seeds.

7. The entire process is managed automatically using programmed instructions/commands written in the Arduino IDE.

8. This ensures proper seed spacing & efficient watering during farming tasks.

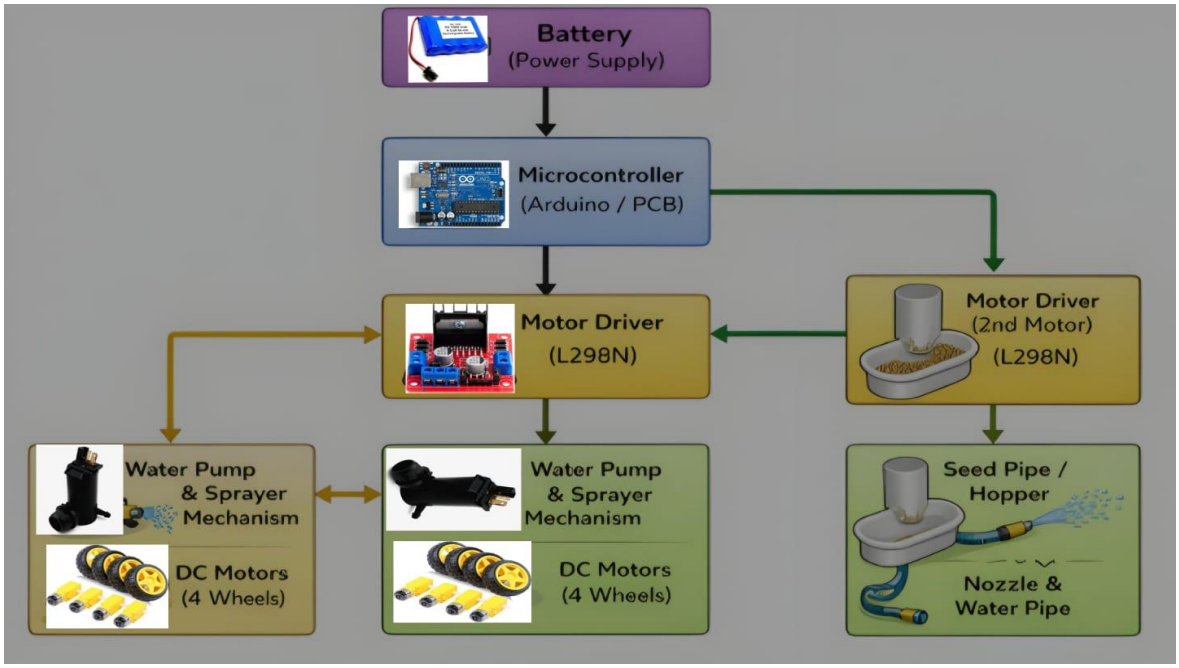
D. Advantages

- Assists smart farming techniques
- Saves time & energy
- Decreases water wastage
- Low cost compared to large farming machines
- Decreases manual labor in farming
- Increases efficiency & productivity
- Ensures precise seed placement

E. Application

- Crop plantation & irrigation systems
- Automated greenhouse farming
- Smart farming technologies
- Agricultural research fields
- Compact farming operations
- Accurate agriculture systems

Block Diagram:



RESULTS AND DISCUSSION

The multipurpose farming robot was examined in a controlled field environment to evaluate its performance & operation. The DC motors allowed smooth movement of the robot across the field, while the seed sowing mechanism successfully placed seeds at regular intervals. The water spraying system distributed water effectively through the nozzle, ensuring proper irrigation of the planted seeds. The Arduino-based control system controlled all operations efficiently & maintained synchronization between movement, seed sowing, & water spraying. The experimental results display that the robot can decrease manual effort and enhance farming efficiency. However, enhancements like advanced sensors & GPS-based navigation could further increase the precision & automation of the system.

CONCLUSION

The multipurpose farming robot gives an efficient solution for advance agricultural practices. By combining automation, robotics, & microcontroller technology, the system can perform multiple farming operations like seed sowing & water spraying with minimum human involvement. The usage of automated machines supports decrease labor costs, save time, & improve productivity in farming operations. This technology represents an crucial step toward the advancement of smart agriculture & precision farming systems.

FUTURE WORK

- Advancement of mobile app control for remote monitoring
- Integration of soil moisture sensors for smart irrigation
- GPS-based navigation for autonomous field movement
- Integration of fertilizer spraying system
- Usage of AI for crop monitoring & decision-making
- Solar-powered battery system

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